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NAVIGATIONAL RISK - JAMMERLAND BUGT WIND FARM

Navigational Risk Assessment Jammerland Bugt Offshore Wind Farm

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Assessment of the navigational risk associated with establishment of the Omø Syd Offshore Wind Farm

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Nomenclature

AIS Automatic Identification System

EIA Environmental impact assessment

HAZID Hazard Identification

IMO International Maritime Organization

IWRAP IALA Waterway Risk Assessment Programme

1 SUMMARY

Jammerland Bugt Offshore Wind Farm is a project subject to pre-investigations under the "open-door" arrangement issued by Danish Energy Agency dated march 2014. The scope of the present report is to assess the navigational risk associated with establishment of the Jammerland Bugt Offshore Wind Farm

The overall approach for this navigational risk assessment follows IMO's (international Maritime Organization) guidelines for evaluation of navigational safety assessment. A stepwise approach is adopted meaning that results are presented after each step and evaluated together with the Danish Maritime Authority (Søfartsstyrelsen) whether or not the next step needs to be executed.

- Step 1: A frequency analysis based on ship traffic and proposed offshore wind farm layout is executed and results are presented to the Danish Maritime Authority.
- Step 2: If the Danish Maritime Authority does not find it possible to conclude from the results of the frequency analysis that the navigational risks will be acceptable, a consequence analysis must be executed and combined with the frequency results. The navigational risk assessment will then be updated with the resulting risk derived by combining the frequency and the consequence analyses.
- Step 3: If the Danish Maritime Authority cannot approve the estimated risk, possible risk reducing measures have to be identified, analyzed and adopted if considered feasible. This risk reduction process must continue until the risk reaches an acceptable level. Otherwise it has to be concluded that the project will not be feasible when required to be associated with an acceptable ship collision risk.

For the present Jammerland Bugt Offshore Wind Farm it is judged that Step 1 is sufficient for the risk assessment. This implies that only a frequency analysis is carried out for the present study. The ship traffic around the proposed area for the Jammerland Bugt Offshore Wind Farm is established based on available AIS data and used as the basis for the navigational risk assessment. The HAZID report concludes that the hazards related to navigational risk are all related to the risk of ships colliding with a turbine or ship-ship collision due to the presence of the Offshore Wind Farm. A wind farm layout consisting of 80 turbines of 3MW (240 MW total) has been used as the worst case scenario (this is a scenario that is expected to produce the largest navigational risk) for this evaluation.

The frequency analysis gives a return period for ship-wind turbine collisions of 111700 years for powered collisions (i.e., typical human error), and 5873 years for drifting collisions (i.e., typical technical errors). The combined return period for powered and drifting collision is thus estimated to 5580 years. The largest contribution to the calculated collision return period is from ship traffic on the north and south going route H west of the wind farm. The risk of ship-ship collision and grounding around the offshore wind farm under existing conditions has been compared to the imposed traffic change due to the wind farm and is evaluated to be insignificant.

Based on these evaluations it is judged not to be necessary to perform a consequence analysis (Step 2) and, hence, neither to perform a detailed evaluation of risk reducing measures (Step 3). The conclusions from the frequency analysis (Step 1) indicate that the occurrence of ship-turbine collisions will be low and hence the increase in navigational risk due to establishment of the Jammerland Bugt Offshore Wind Farm is acceptable.

The impact on the navigational risk during the installation and decommissioning phases has not been evaluated since there are still too many unknown parameters to complete this analysis. The risk assessment for the installation and decommissioning would normally be part of the scope of work for the appointed contractor.

2 INTRODUCTION

On February 22 2012 European Energy A/S applied for a permit for feasibility studies and preparation of an EIA for the establishment of an offshore wind farm at Jammerland Bugt. The permit was given by Energistyrelsen on March 3 2014. In connection with the feasibility studies a navigational risk analysis shall be carried out.

DNV GL has been contracted to perform a navigational safety analysis in connection with the preparation of the environmental impact assessment (EIA) for the Jammerland Bugt Offshore Wind Farm.

2.1 Objectives

The objective of the present navigational risk assessment is to evaluate how and to what extent the ship traffic in the area will be influenced by the Jammerland Bugt Offshore Wind Farm and to identify and estimate any associated increase in the navigational risk in the region near the wind farm.

3 PROJECT DESCRIPTION

Jammerland Bugt Offshore Wind Farm is a near shore farm. The entire survey area is shown in figure 3.1. Refer to appendix A for a navigational chart.

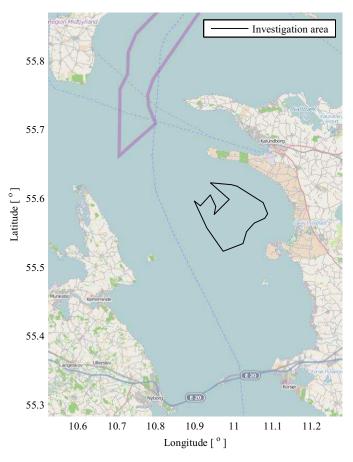


Figure 3.1

3.1 Installations offshore

Jammerland Bugt Offshore Wind Farm will be located within an approximate 69 km² survey area, which covers an area, situated between the Great Belt bridge and Kalundborg. Water depths in the area vary between 4 and 20 m. The offshore wind farm will possibly be established with a maximum capacity of 240 MW and will possibly take op the whole survey area.

Turbine capacity	Rotor diameter	Total height	Hub height	Max number
3MW	112 m	150 m	94 m	80 pcs
6MW	154 m	199 m	112 m	35 pcs

Table 3.1: Specifications of possible turbines

The power will be exported directly to land thus no offshore substation will be needed.

3.2 Wind farm layout

The possible positions for the 80 3MW and 35 6MW turbines are shown in appendix C.1-C.2. The turbine layout is shown in figure 3.2.

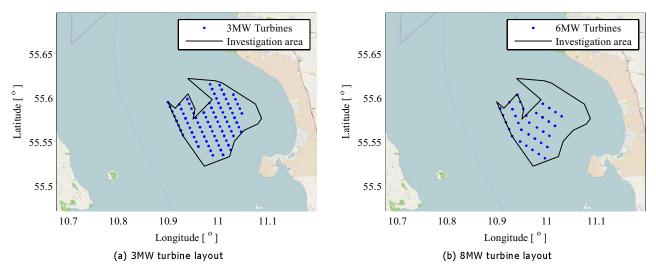


Figure 3.2: Turbine layouts

4 BACKGROUND

The navigational risk assessment presented in the present report is part of the total EIA (Environmental Impact Assesment) for the Jammerland Bugt Offshore Wind Farm project.

The overall approach for this navigational risk assessment follows IMO's (international Maritime Organization) guidelines for evaluation of navigational safety assessment. A stepwise approach is adopted meaning that results are presented after each step and evaluated together with the Danish Maritime Authority (Søfartsstyrelsen) whether or not the next step needs to be executed.

- Step 1 A frequency analysis based on ship traffic and proposed offshore wind farm layout is executed and results are presented to the Danish Maritime Authority.
- Step 2 If the Danish Maritime Authority does not find it possible to conclude from the results of the frequency analysis that the navigational risks will be acceptable, a consequence analysis must be completed and combined with the frequency results. The navigational risk assessment will then be updated with the resulting risk derived by combining the frequency and the consequence analyses.
- Step 3 If the Danish Maritime Authority cannot approve the estimated risk, possible risk reducing measures have to be identified, analyzed and adopted if considered feasible. This risk reduction process must continue until the risk reaches an acceptable level. Otherwise it must be concluded that the project will not be feasible when required to be associated with an acceptable ship collision risk.

The basis for the evaluation covered in Step 1 (The frequency analysis) is described in the following subsections. The objective of Step 1 is to estimate the frequency of ship collisions with the wind turbines and this is performed based on a worst case layout of the offshore wind farm. The results are initially used to assess if the risk associated with collisions can be concluded acceptable without quantifying the consequences of these collisions. This would be the case if the frequencies are so low that the associated risks would be acceptable even with the most conservative assessment of the consequences. If this is not the case Step 2 (The consequence analysis) has to be carried out.

4.1 Method

The following describes the method for performing Step 1, - the frequency analysis. The frequency analysis is based on acknowledged mathematical models typically used for such analyses and with input based on historical (statistical) data. The applied calculation tool IWRAP MKII is a part of the IALA Recommendation [IALA O-134] on risk management.

4.1.1 Analysis tool

The IWRAP MKII software calculates the probability of collision or grounding for a vessel operating on a specified route. The applied model for calculating the frequency of grounding or collision accident involves the use of a so-called causation probability that is multiplied onto a theoretically obtained number of grounding or collision candidates. The causation factor models the probability of the officer on the watch not reacting in time given that he is on collision course with another vessel (or – alternatively – on grounding course), refer to Engberg [2010] for detailed theoretical model description.

A description of the ship traffic constitutes the central input for a navigational risk assessment. Automatic Identification System (AIS) data provides a detailed geographic and temporal description of the ship traffic in a region and has been used as the primary data basis. Because the predominant part of the ship traffic is following navigational routes – which can be more or less well defined – the modelling of the ship traffic and the associated models of the risk of collisions and groundings usually adopts a route based description of the traffic.

The ship traffic description based on AIS is thus subsequently used as basis for definition of the routes in the probabilistic model in IWRAP MKII.

4.1.2 Risk scenarios

Installation of an offshore wind farm will introduce obstacles that the ship traffic has to avoid. If not successful in doing this a collision to a wind turbine will be the result. However, the deviations required of the ship traffic to avoid the wind turbines may also increase the potential for ship-ship collisions. A navigational risk analysis shall therefore cover the following four risk contributions:

- Ship-turbine collision risk for powered vessels (i.e., typically human error).
- Ship-turbine collision risk for drifting vessels (e.g., vessel with technical error).
- Changes in ship-ship collision risk due to increased traffic density around the offshore wind farm area.
- Changes in ship grounding risk due to changed traffic pattern around the offshore wind farm area.

The frequency analysis shall determine how often the above-mentioned three scenarios are expected to occur when the offshore wind farm has been introduced and based on this it can initially be judged if the risk associated with such collisions is readily acceptable. If not, the likely consequences of the collisions have to be determined to establish the fully detailed risk picture.

4.2 Worst case assumptions

As described in section 3.1 either 3MW or 6MW turbines are to be installed. Since the final layout of the turbines in the offshore wind farm is not known at present, the navigational risk assessment is performed such that it will represent a worst case for all possible turbine layouts i.e. both with regards to turbine size and location of the turbines within the offshore wind farm area.

The collision frequency analysis is based on a layout of wind turbines that, in the context of navigational risk, is considered as the worst case scenario. The chosen worst case scenario is 80 3MW turbines since this will result in the highest risk of collision. It is noted that a layout with 35 6MW turbines would take up approximately the same area, but the lower number of turbines would present fewer obstacles to the ship traffic which would lead to a reduced potential of ship collisions. The 80 3MW turbines are in the worst

case scenario distributed over the entire offshore wind farm area since this represents the case where the existing ship traffic will be disturbed the most.

The diameter of the tower at the water surface, which is relevant for the ship-turbine collision is assumed to be 10 meters.

4.3 Before and after

The ship traffic before and after the construction of the wind farm will be modeled in order to compare the impact of the offshore wind farm on the navigational risk. It is assumed that some traffic routes will change and furthermore fishing and leisure vessels will change patterns. Ship-ship collision and grounding of ships will thus be modeled in cases predicting before (i.e. existing conditions) and after construction of the wind farm.

Scenario	Existing routes	Relocated routes	Turbines included
1 (Before)	x		
2 (After)	x	x	Х

Table 4.1: Calculated scenarios

5 EXISTING CONDITIONS

In the context of navigational risk the relevant existing conditions are constituted by the ship traffic in the area. The existing ship traffic in the vicinity of the offshore wind farm area is shown in figure 5.1. The figure is based on AIS data collected in the period from October 1 2013 to September 30 2014 and hence represents the existing conditions undisturbed by the presence of an offshore wind farm. The collection of ship traffic data and subsequent modifications in order to use it for the frequency analysis is described in the following subsections.

5.1 Ship traffic based on AIS data

This subsection describes the ship traffic used as input for the frequency analysis. The ship traffic is determined from regional AIS data collected for twelve months. The AIS data handled in the analysis is within the following geographic bounds:

	56°13.335′ N	
008°49.836′ E		014°34.969′ E
	54°22.917′ N	

Table 5.1: Geographic bounds of AIS

The mapped AIS data and its extents are shown in figure 5.1

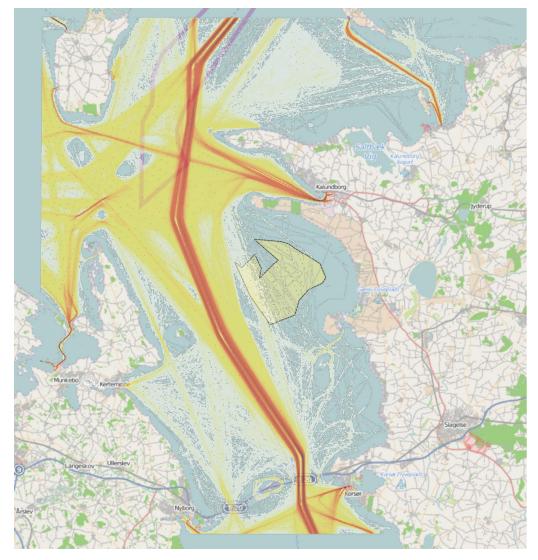


Figure 5.1: Ship traffic density based on AIS data from October 1 2013 to September 30 2014. The turbine area is shown for information only

5.2 Analysis of AIS data

The AIS data consists basically of successive position reports from each individual vessel that are within the selected geographic area. The first step in the analysis is to separate the position reports for each vessel, arrange them chronologically and combine them in sequence to form tracks that describe their passage within the area. These tracks form the basis for the subsequent analysis. The first result of the analysis is the density of tracks that is shown in figure 5.1.

Of main regard for the wind farm the traffic density is dominated by the densely trafficked corridor, route H, that is passing through Great Belt.

The traffic modelling is approximated by poly-linear center-lines – the route – and a probabilistic description of the traffic distribution transverse to this ideal center line. Based on successive definition of routes and association of the AIS tracks to these routes, a set of routes have been found necessary and relevant in order to model the ship traffic considered in the present study which is of particular concern to the proposed Jammerland Bugt Offshore Wind Farm.

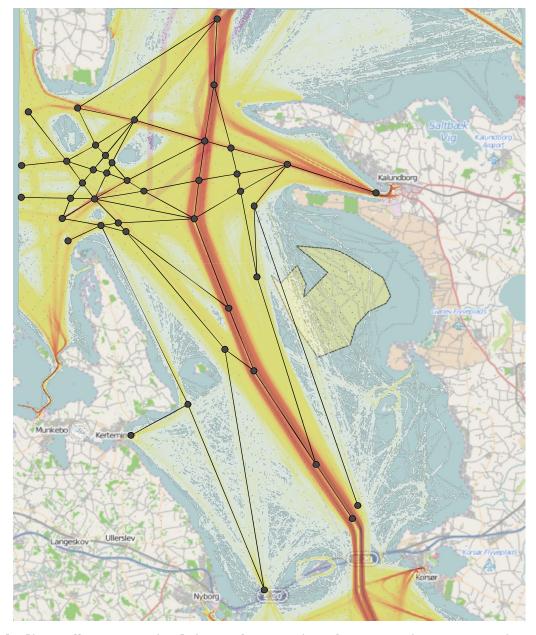


Figure 5.2: Ship traffic routes and AIS data, refer appendix D for route and waypoint numbers. Turbine area shown for information only

Based on the AIS and associated routes in figure 5.2 (refer appendix D for waypoint and route details), it is evident that ship traffic on some routes are passing through the site or in close proximity, and will thus adapt to the presence of the proposed Jammerland Bugt Offshore Wind Farm. It is noted that LEG_39 is passing directly through the proposed Jammerland Bugt Offshore Wind Farm. Hence, the traffic pattern after the offshore wind farm has been established will change. Section 6 deals with the anticipated reaction of the ship traffic due to the presence of the wind farm i.e. the traffic will tend to stay outside the wind farm and at a reasonable distance.

The association of routes does not necessarily utilize all the observed tracks in the AIS database. However all tracks has been evaluated and the ones found important for the present analysis has been included.

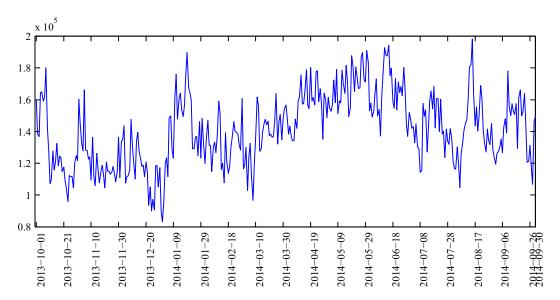


Figure 5.3: Variation of number of AIS records per day for the survey period

5.3 Ship classification

The ships are classified according to information contained in AIS signal message 5 (see ITU-R-1371-5 section 3.3 "Ship static and voyage related data" and section 3.3.2 "Type of ship"). Based on the identifier number contained in message 5 the following ship types are categorized as follows:

				Ship type		
Type Of Ship And Cargo	Fishing ship 30	Pleasure boat 37	Support ship 31-35 50-59	Passenger ship 40-49 60-69	General cargo ship 70-79	Oil Products tanker 80-89

- * All tankers are placed into the category "Oil Products tanker"
- * All cargo ships are placed into the category "General cargo ships"
- * Passenger ships which travels faster than 30 knots are placed in the category "High speed ferry"
- * If AIS is class B and not "Fishing ship" then "Pleasure boat"

Table 5.2: Ship classification according to AIS identifier number

5.4 Modeling of traffic distribution across routes

The ship traffic as identified through the AIS data has been associated with ideal – or generic – routes described in terms of the ideal centerlines. In order to calculate the risk of collisions to the offshore wind farm structures it is required that the deviation of the ship traffic from these ideal centerlines is described by a probabilistic model.

In some cases the description of the deviations can be extracted from the observed deviations – i.e., via the spread of the observed traffic density. But, in other cases, the establishment of the proposed offshore wind farm will impose changes to the navigational pattern to ensure a safe passing distance to the offshore wind farm structures. In these cases the spread and distribution type of the traffic has to be assumed on the basis of the presently observed spread combined with the proximity and restriction that the offshore wind farm structures is considered to constitute to the ship traffic.

The transverse distribution is composed of a number of superposed probability distributions (normal and uniform) which are fitted to the recorded AIS data. A graphic overview of the fitted distributions are shown in figure 5.4.

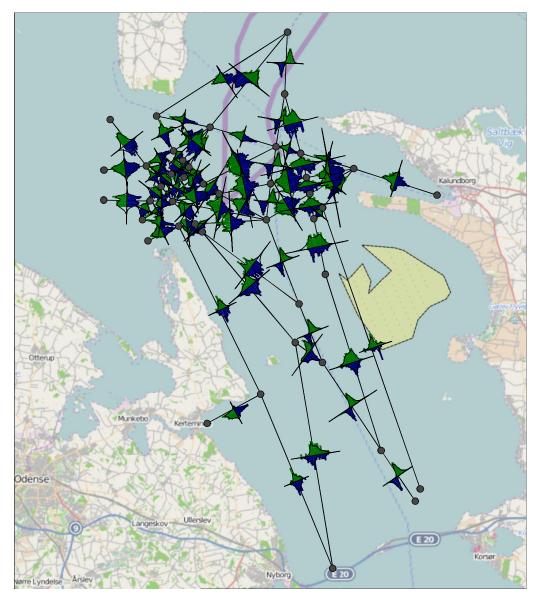


Figure 5.4: Defined routes and distributions. Turbine area shown for information only

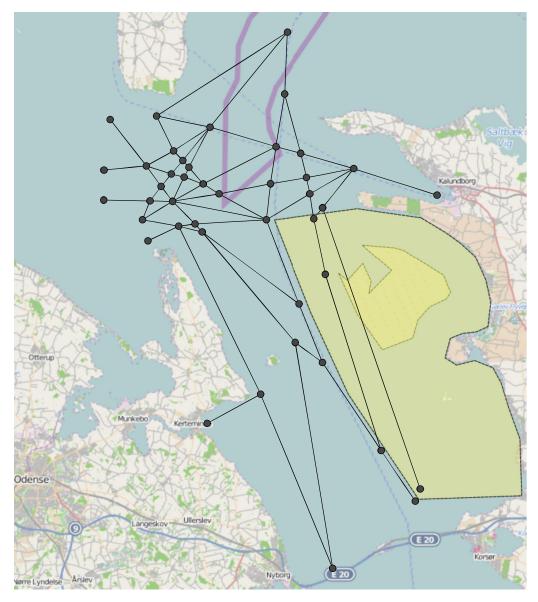


Figure 5.5: Leisure traffic modeled in the yellow area. Turbine area shown for information only

5.5 Traffic areas

By traffic area is understood that traffic that do not follow ordinary routes. The area traffic is composed of leisure crafts and fishing vessels. These vessels will cross the routes at which the line traffic operates at random angles. The number of collisions between the area traffic and the line traffic is calculated by assuming that the area traffic crosses the route the line traffic operates on at eight different directions.

The traffic areas is included to predict the ship-ship collision frequencies and does not influence the ship grounding or ship-turbine collision results.

Since the traffic is not based on AIS statistics it is thus defined manually in terms of size, number and some parameters determining how the traffic is assumed to behave during a year.

5.5.1 Leisure traffic

The leisure vessels will usually travel in patterns that are more irregular than that of the merchant ship traffic. As mentioned in the HAZID report DNV GL [2014] these traveling patterns are not well described in the route structure that is used for the merchant traffic, and a different more diffuse modeling of this ship traffic is required for use in a frequency analysis.

It is evaluated that approximately 500 leisure vessels are present in Jammerland Bugt during a year.

Length	Number of ships	Number of days	Visits	Movement time	Stationary time
[m]	[per year]	[per ship per year]	[per day]	[hours per visit]	[hours per visit]
15 m	500	20	1	8	0

Table 5.3: Assumed leisure traffic

The leisure vessels are included in the model as a "traffic area". In these areas the vessels will cross the routes at which the line traffic operates at random angels. The number of collisions between the area traffic and the line traffic is calculated by assuming that the area traffic crosses the route the line traffic operates on, at eight different directions.

It is evaluated that the traffic on route H will be unaffected by the presence of the farm and the anticipated response of the leisure vessels. The leisure traffic area is thus modeled as an traffic area extending from Zealand and towards the boundary of route H in Great Belt see figure 5.5.

5.5.2 Fishing traffic

As during the HAZID DNV GL [2014] it was estimated that approximately 45 fishing vessels at the size of around 12m are not covered by AIS. The assumed fishing traffic is shown in table 5.4 (note that size and number of ships has been taken as 20 m and 100 respectively). It is assumed that these vessels are present in the same area as shown in figure 5.5.

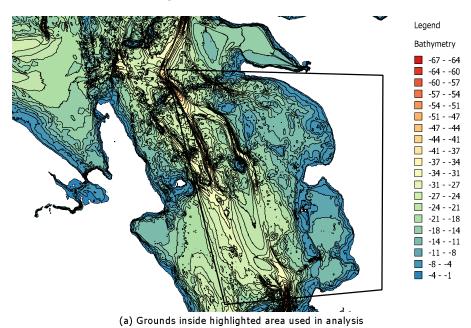
Length	Number of ships	Number of days	Visits	Movement time	Stationary time
[m]	[per year]	[per ship per year]	[per day]	[hours per visit]	[hours per visit]
20	100	100	1	6	2

Table 5.4: Assumed fishing traffic

5.6 Modeling of grounds

The grounds in the area are as shown in figure 5.6a. The wind farm will be located at water depths ranging between 10 to 4m in the bay of Jammerland Bugt. The wind farm will be partly shielded by the grounds "Lysegrunde" (Southbound traffic on route H) and "Elefantgrunde" (Northbound traffic on route H).

The grounds inside the marked area in figure 5.6a have been included in the model.





(b) Bathymetry imported into analysis. The darker surrounding area defines a water depth enabling emergency anchoring for ships outside the detailed bathymetry area

Figure 5.6

6 REVISED CONDITIONS

The presence of the offshore wind farm under investigation is assumed to result in that some of the ship traffic will relocate to avoid passing through the offshore wind farm. The routes used to model these components of the ship traffic in the frequency analysis will be adjusted accordingly based on the assumed future behavior of this traffic i.e. how the traffic will tend to relocate.

In the analysis it is assumed that ship traffic will not travel through the farm. The proposed revisions to these routes are discussed in the following.

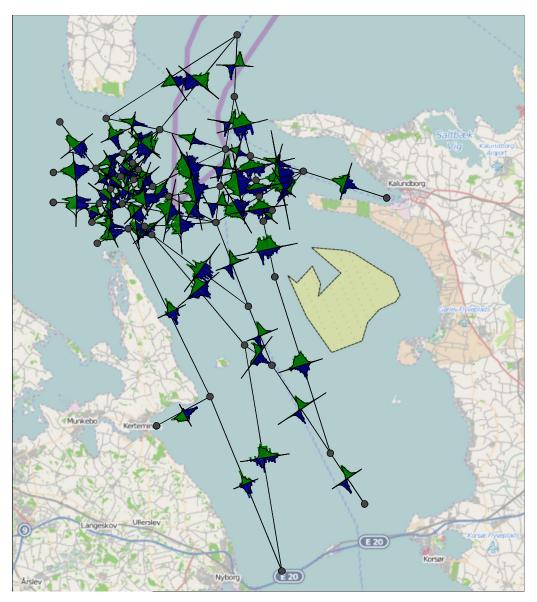


Figure 6.1: Revised routes due to wind farm.

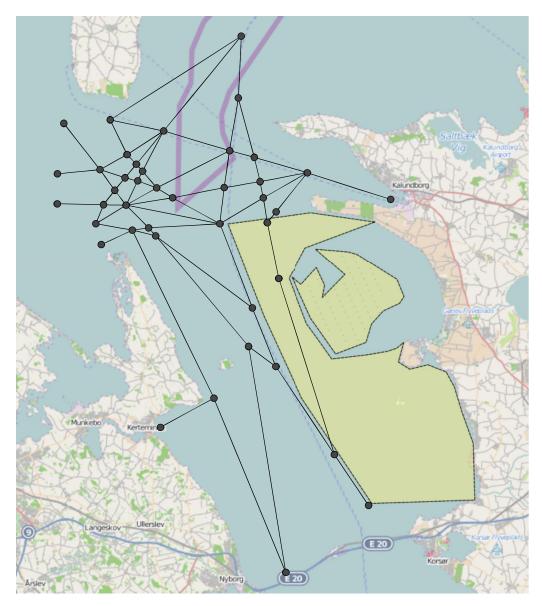


Figure 6.2: Revised traffic area due to windfarm

6.1 Revised modeling of traffic distribution across routes

As mentioned in section 5.2 the traffic on LEG_39 is passing straight through the wind farm area . It is predicted that the traffic will respond as in the following:

LEG 39 Traffic is mainly consisting of support vessels to and from Kalundborg Harbour. It is evaluated that this traffic will follow route 2 in the future thus increasing probability of ship-ship collisions on the route.

Refer to appendix D for route information.

6.2 Leisure traffic

As discussed in the HAZID DNV GL [2014] the wind conditions inside the wind farm is not ideal for sailing purposes, leisure vessels will likely tend to stay out of the wind farm area. The revised traffic area is shown in figure 6.2.

6.3 Fishing traffic

As discussed in the HAZID DNV GL [2014] the foundations of the turbines will create an artificial reef which can give beneficial conditions for certain types of fish. It is thus not expected that the fishing pattern will be different from the one described in section 5.5.2. The vessels are however conservatively (with regard to ship-ship collision) assumed to be in the same area as the leisure traffic discussed above.

7 IMPACT ASSESMENT DURING INSTALLATION PHASE

The present report focuses on the operation phase. Key parameters necessary for performing a thorough risk assessment of the installation phase (installation technique, type of installation vessels and transport route of components from onshore fabrication facility to the offshore site etc) will be chosen by the contractor. Hence the risk assessment for the installation phase cannot be carried out before the necessary decisions have been taken by the appointed contractor. The risk assessment would normally be part of the scope of work for the appointed contractor. Furthermore the choice of foundation type for the turbines and the amount of turbines to be installed (80 3MW or 35 6MW) will also influence the duration of the installation and hence also the risk assessment. It is assumed that a "safety zone" will be laid out during the installation work in order to protect the installation vessels, the personnel and the installed assets from collision with incoming vessels.

8 IMPACT ASSESMENT DURING OPERATION

8.1 Hazard identification

In the HAZID report DNV GL [2014] hazards for the operation phase have been identified. The majority of the identified hazards relate to the risk that ships in the area will collide with a turbine

8.2 Collision and grounding frequencies

8.2.1 Ship-turbine collision

The ship-turbine collision frequencies are calculated for the two scenarios below:

- · Collision from drifting vessels
- · Collision from powered vessels

The frequency results are derived based on the worst case scenario defined in section 4.2 which is evaluated to constitute the largest risk of ship collision. The ship routes and traffic are as defined in section 6 and reflects the presence of of the Jammerland Bugt Offshore Wind Farm. It is noted that the calculated collision frequencies cover all cases of collision, i.e. both minor collisions as well as severe collisions where repair of ship is needed.

The accumulated results are presented in table 8.1

	Powered collision	Drifting collision	Sum
All routes & all vesseltypes	111700 years	5873 years	5580 years

Table 8.1: Collision return period in years

From table 8.1 it is seen that the total return period for collisions is estimated to 5580 years without any risk reducing measures implemented. The cumulative collision frequencies for powered and drifting vessels distributed on ship routes are shown in figure 8.1.

This is under the assumption that the traffic will relocate to avoid passing through the wind farm as discussed in section 6.

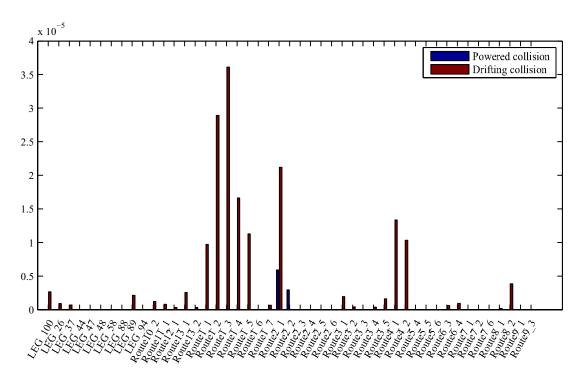


Figure 8.1: Collision frequencies for powered and drifting vessels distributed on ship routes

8.2.2 Ship-ship collision and grounding

In order to evaluate the change in navigational risk in the area a before and after scenario has been established as discussed in section 4.3. The accumulated results are presented in table 8.2.

	Grounding incidents	Ship-ship collision incidents
Before	21.62 years	11.09 years
After	21.62 years	11 years

Table 8.2: Impact on navigational risk due to presence of wind farm. Return period in years.

Detailed results distributed on ship routes are shown in appendix F.

8.3 Total impact

From the hazard identification process, refer section 8.1, it is determined that the main risk is posed by ship-turbine collision, ship-ship and grounding incidents.

This risk is evaluated by performing a frequency analysis with results provided in table 8.3.

	Phase	Impact
Ship-turbine collision	Operation	Return period 5580 years
Ship-ship collision	Operation	Return period 21.62 years before and 21.62 years after
Grounding	Operation	Return period 11.09 years before and 11 years after

Table 8.3: Total impact

Based on results shown in table 8.3 it was not deemed necessary to perform a consequence analysis or to perform a detailed evaluation of risk reducing measures. The conclusions from the frequency analysis alone indicate that the occurrence of ship-turbine collisions, ship-ship and grounding incidents will be low and hence the increase in navigational risk due to establishment of the Jammerland Bugt Offshore Wind Farm is acceptable.

9 IMPACT ASSESSMENT DURING DECOMMISSION

Risk of collision during the decommissioning phase has not been evaluated in present report. This should be the responsibility of the appointed contractor taking care of the decommissioning and should not be evaluated in detail before the offshore wind farm is close to the end of the defined service life.

10 MITIGATION MEASURES

It is not found necessary to implement mitigation measures in addition to the usual precausions that by defailt are required for offshore installations, refer conclusion in section 8.3. These default requirements include that; turbine foundations must be painted yellow, turbine foundations must have identification signs that are illuminated, and the offshore wind farm must have light marking. These measures have already been taken into account in the risk assessment since the risk calculation models have been calibrated against observed collisions and these have happened under usual conditions and thus under the precautions normally required. Additional mitigation measures are as previously stated not included in the risk assessment.

11 CONCLUSION

The impact of the Jammerland Bugt Offshore Wind Farm on the navigational risk is evaluated based on hazards identified in a HAZID and a subsequent calculation of collision frequencies. The risk assessment is performed on this basis.

In the HAZID report DNV GL [2014] the majority of identified hazards for the operation phase relate to the risk that ships in the area will collide with a turbine.

A frequency analysis is performed to evaluate the likelihood of ship-turbine collision. An offshore wind farm layout consisting of 80 turbines of 3MW distributed over the entire offshore wind farm area is used as worst-case scenario for the assessment. The ship traffic is established based on AIS data and routes have been adjusted where necessary to reflect the reaction of the ship traffic to the presence of the offshore wind farm.

The frequency analysis gives a return period for ship-wind turbine collisions of 111700 years for powered collisions (i.e., typical human error), and 5873 years for drifting collisions (i.e., typical technical errors). The combined return period for powered and drifting collision is thus estimated to 5580 years.

The change in ship-ship collision risk and the increase of grounding incidents has been found to be insignificant.

Based on these evaluations it is not deemed necessary to perform a consequence analysis (Step 2) or to perform a detailed evaluation of risk reducing measures (Step 3). The conclusions from the frequency analysis alone (Step 1) indicate that the occurrence of ship-turbine collisions will be low and hence the increase in navigational risk due to establishment of the Jammerland Bugt Offshore Wind Farm is acceptable.

The impact on the navigational risk during the installation and decommissioning phases has not been evaluated since too many parameters are unknown. The risk assessment for the installation and decommissioning would normally be part of the scope of work for the appointed contractor.

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A Navigational chart

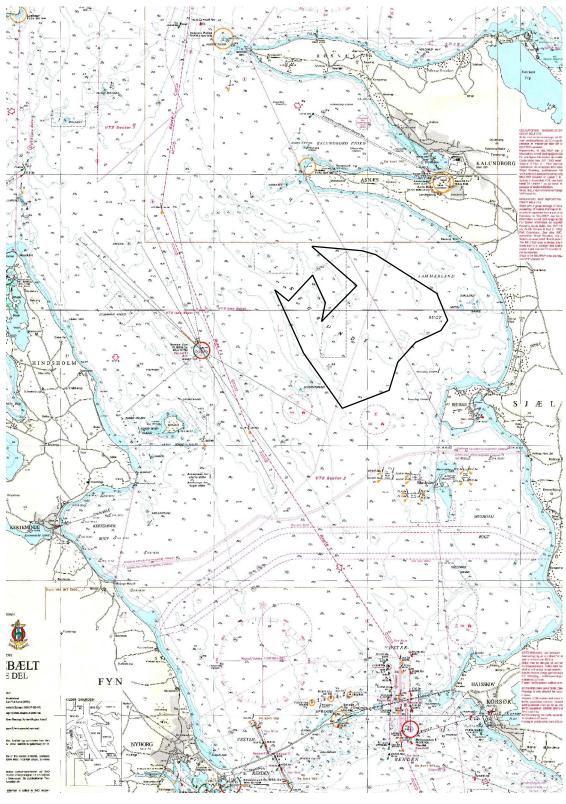


Figure A.1

B Probabilistic model assumptions

Already in 1974 Fujii and Mizuki [1974] and also MacDuff [1974] initiated more systematic and risk based approaches for grounding and collision analysis. MacDuff studied grounding and collision accidents in the Dover Strait and calculated a theoretical probability of both the grounding and the collision event. This probability was calculated by assuming all vessels to be randomly distributed in the navigational channel. MacDuff denoted the thus obtained probability the geometric probability, since this probability was entirely based on a geometric distribution of ships that were "navigating blind". By comparing to the observed number of grounding and collision it was found that the geometric probability predicted too many events and a correction factor P_c was introduced to account for the difference. The correction factor was denoted the causation probability and it models the vessels and the officer of the watch's ability to perform evasive manoeuvres in the event of a potential critical situation.

Using an approach similar to MacDuff [1974], Fujii and Mizuki [1974] introduced a probability of mismanoeuvres on the basis of grounding statistics for several Japanese straits. For the considered straits the probability was found to be in the range from 0.6E-4 to 1E-3.

The IWRAP default values for human failure which have been applied are shown in the top of table B.1. The values are mainly rooted in the observations from Fujii and Mizuki [1998]. The assumed machine failure relevant parameters are reflected in the bottom of table B.1.

Human failure relevant parameters

Ship-ship collision incidents	Causation factors
Merging	1.3E-4
Crossing	1.3E-4
Bend	1.3E-4
Headon	0.5E-4
Overtaking	1.1E-4
Area moving	0.5E-4
Area stationary	0.5E-4
Ship grounding incidents	
Grounding - forget to turn	1.6E-4
Ship-turbine collision incidents	
Collision - forget to turn	1.6E-4
Ship type specific reductions	Causation reduction factors
Passenger ships	20
Fast ferries	20

Machine failure relevant parameters

Drift speed Probability of successful anchoring	1 knot(s) 0.98
Probability of self-repair	$p(t) = \begin{cases} 0 & t \le 0.25\\ \frac{1}{1.5(t - 0.25) + 1} & t > 0.25 \end{cases}$
Blackout frequencies RoRo and passenger ships Other vessels	0,1 per year 1,75 per year
Drobabilty of drift direction	

Probabilty of drift direction

N	NE	E	SE	S	SW	W	NW
9.1%	18.2%	18.2%	18.2%	9.1%	9.1%	9.1%	9.1%

Table B.1

C Turbine coordinates

C.1 Turbine coordinates 3MW

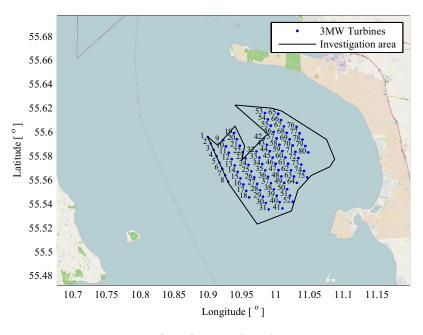


Figure C.1: 3MW turbine layout

	Longitude [°]	Latitude [°]
1	55.5957	10.8999
2	55.5903	10.9042
3	55.5850	10.9084
4	55.5797	10.9127
5	55.5744	10.9170
6	55.5691	10.9213
7	55.5638	10.9255
8	55.5585	10.9298
9	55.5932	10.9223
10	55.5879	10.9266
11	55.5825	10.9309
12	55.5772	10.9352
13	55.5719	10.9394
14	55.5666	10.9437
15	55.5613	10.9480
16	55.5560	10.9522
17	55.5507	10.9565
18	55.5454	10.9608
19	55.5990	10.9385
20	55.5937	10.9428
21	55.5884	10.9471
22	55.5831	10.9514
23	55.5778	10.9556
24	55.5725	10.9599
25	55.5672	10.9642
26	55.5619	10.9685

27	55.5565	10.9727
28	55.5512	10.9770
29	55.5459	10.9813
30	55.5406	10.9855
31	55.5353	10.9898
32	55.5838	10.9717
33	55.5785	10.9760
34	55.5732	10.9803
35	55.5679	10.9846
36	55.5625	10.9888
37	55.5572	10.9931
38	55.5519	10.9974
39	55.5466	11.0017
40	55.5413	11.0017
41	55.5360	11.0102
42	55.5946	10.9828
43	55.5893	10.9871
44	55.5840	10.9914
45	55.5787	10.9956
46	55.5734	10.9999
47	55.5680	11.0042
48	55.5627	11.0085
49	55.5574	11.0127
50	55.5521	11.0170
51	55.5468	11.0213
52	55.5415	11.0255
53	55.6158	10.9843
54	55.6105	10.9885
55	55.6052	10.9928
56	55.5999	10.9971
57	55.5946	11.0014
58	55.5892	11.0057
59	55.5839	11.0099
60	55.5786	11.0142
61	55.5733	11.0185
62	55.5680	11.0228
63	55.5627	11.0270
64	55.5574	11.0313
65	55.6152	11.0036
66	55.6099	11.0079
67	55.6045	11.0122
68	55.5992	11.0165
69	55.5939	11.0208
70	55.5886	11.0250
71	55.5833	11.0293
72		11.0293
73	55.5780 55.5727	11.0336
74	55.5673	11.0421
75	55.5620	11.0464
76	55.6041	11.0310
77	55.5988	11.0353
78	55.5935	11.0396
79	55.5882	11.0439
80	55.5829	11.0482

C.2 Turbine coordinates 8MW

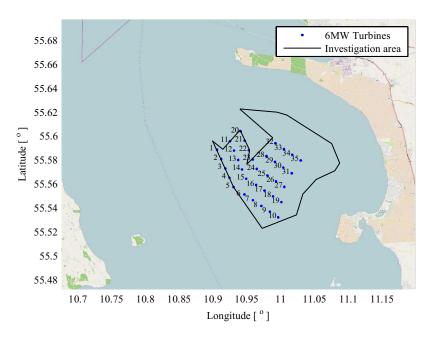


Figure C.2: 8MW turbine layout

	Longitude [°]	Latitude [°]
1	55.5885	10.9061
2	55.5807	10.9121
3	55.5729	10.9182
4	55.5651	10.9243
5	55.5572	10.9304
6	55.5511	10.9464
7	55.5463	10.9589
8	55.5415	10.9714
9	55.5368	10.9839
10	55.5320	10.9964
11	55.5956	10.9252
12	55.5877	10.9312
13	55.5799	10.9371
14	55.5721	10.9431
15	55.5642	10.9491
16	55.5591	10.9637
17	55.5543	10.9762
18	55.5496	10.9887
19	55.5448	11.0012
20	55.6038	10.9409
21	55.5960	10.9469
22	55.5881	10.9528
23	55.5803	10.9588
24	55.5725	10.9648
25	55.5669	10.9805
26	55.5622	10.9929
27	55.5574	11.0055
28	55.5831	10.9790
29	55.5784	10.9915

30	55.5736	11.0040
31	55.5689	11.0165
32	55.5938	10.9923
33	55.5891	11.0048
34	55.5843	11.0174
35	55.5796	11.0299

D Waypoint coordinates and route definitions

D.1 Before scenario

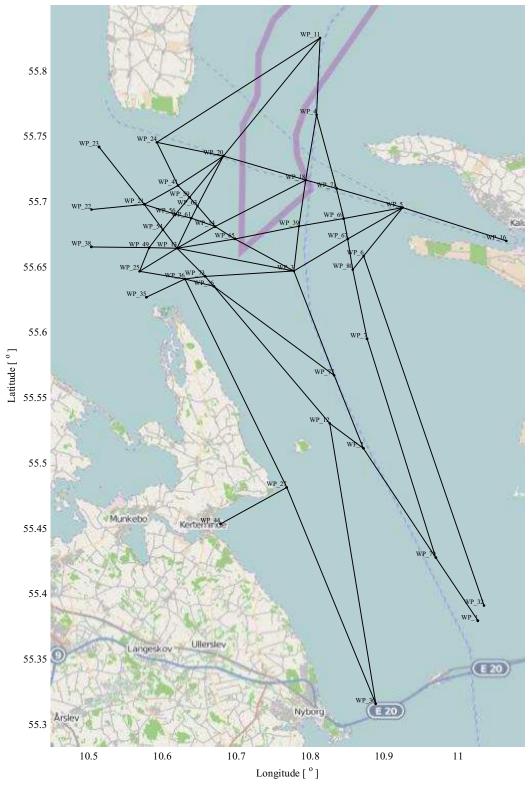


Figure D.1: Waypoints

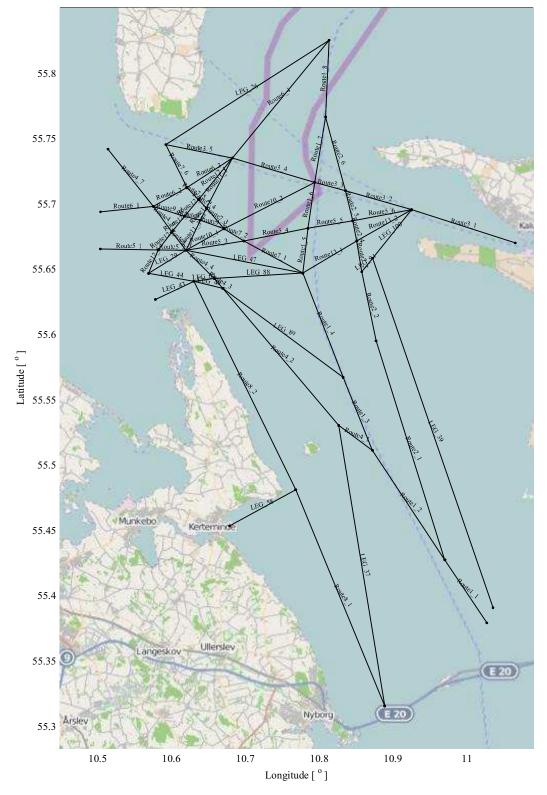


Figure D.2: Routes

	Longitude [°]	Latitude [°]
WP 1	55.3790116	11.0268745
WP 2	55.5110472	10.8720783
WP 3	55.6466894	10.7777749
WP 4	55.7662346	10.8087271
WP 5	55.6952133	10.9250447
WP 6	55.6581	10.87245
WP 7	55.5948298	10.8769562
WP 11	55.8249612	10.8134492
WP 12		10.826311
WP 13	55.6641095	10.619741
WP 14		10.6712726
WP 16		11.0653986
WP 18	55.7161723	10.7939184
WP 20		10.682579
WP 21		10.5753952
WP 22	55.6936529	10.503981
WP 23	55.741629	10.5142355
WP_24	55.7451473	10.592407
WP 25	55.6464571	10.5690843
WP_26	55.6350107	10.6697632
WP_27		10.7682034
WP_30		10.8886594
WP_32	55.3907073	11.0352388
WP_35	55.6265248	10.5783318
WP_36		10.6303024
WP_38	55.6651256	10.503796
	55.6809733	10.7848513
WP_41		10.6211043
WP_44		10.6786207
WP_49		10.5818386
WP_54	00.070202	10.6005113
WP_56		10.6177054
WP_59		10.6367814
WP_61		10.639094
WP_63		10.64731
WP_65		10.6980188
WP_67	55.6712934	10.8509287
WP_69		10.8453729
WP_71		10.8356352
WP_73		10.657681
WP_77		10.8325086
WP_79		10.9700781
WP_80	55.6477178	10.8576159

D.2 After scenario

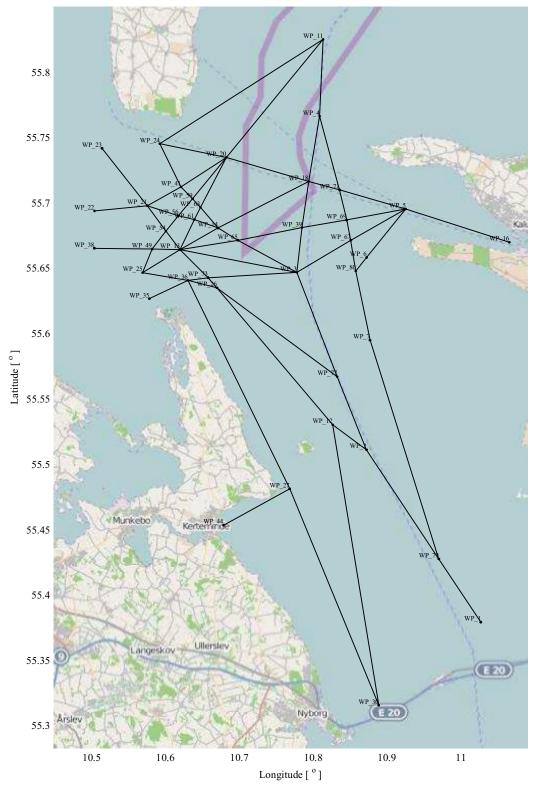


Figure D.3: Waypoints

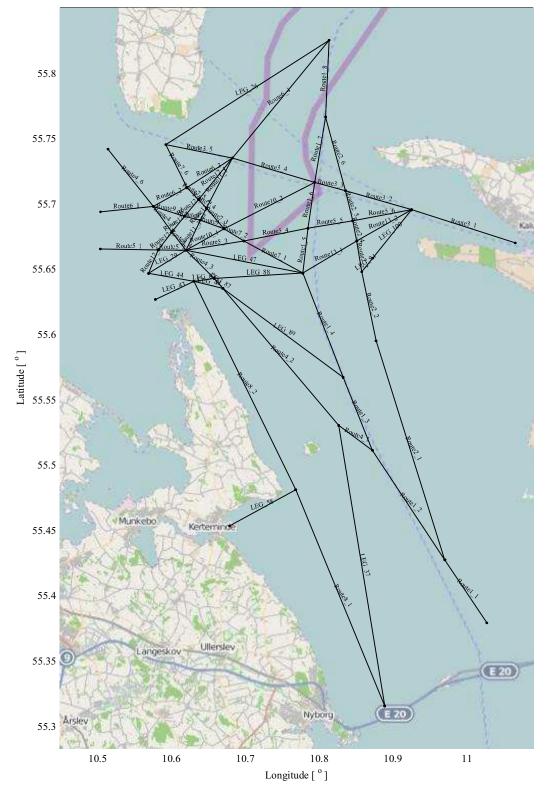


Figure D.4: Routes

Longitud	e [°]	Latitude [°]
WP 1 55.3790		11.0268745
WP 2 55.5110		10.8720783
WP 3 55.6466		10.7777749
WP 4 55.7662	346	10.8087271
WP 5 55.6952		10.9250447
WP 6 55.6581		10.87245
WP_7 55.5948	298	10.8769562
WP_11 55.8249	612	10.8134492
WP_12 55.5301	075	10.826311
WP_13 55.6641	095	10.619741
WP_14 55.6806	61	10.6712726
WP_16 55.6697		11.0653986
WP_18 55.7161	723	10.7939184
WP_20 55.7347		10.682579
WP_21 55.6977		10.5753952
WP_22 55.6936		10.503981
WP_23 55.7416		10.5142355
WP_24 55.7451		10.592407
WP_25 55.6464		10.5690843
WP_26 55.6350		10.6697632
WP_27 55.4810		10.7682034
WP_30 55.3153		10.8886594
WP_35 55.6265		10.5783318
WP_36 55.6404		10.6303024
WP_38 55.6651		10.503796
WP_39 55.6809		10.7848513
WP_41 55.7121		10.6211043
WP_44 55.4531		10.6786207
WP_49 55.6644		10.5818386
WP_54 55.6782		10.6005113
WP_56 55.6901		10.6177054
WP_59 55.7030		10.6367814
WP_61 55.6871		10.639094
WP_63 55.6964		10.64731
WP_65 55.6712		10.6980188
WP_67 55.6712		10.8509287
WP_69 55.6867		10.8453729
WP_71 55.7098		10.8356352
WP_73 55.6426		10.657681
WP_77 55.5668		10.8325086
WP_79 55.4273		10.9700781
WP_80 55.6477	1/8	10.8576159

E Traffic on routes

E.1 Before scenario

				Traffic di	stribution			
LEG 100 LEG 26 LEG 29 LEG 39 LEG 39 LEG 44 LEG 44 LEG 58 LEG 68 LEG 68 LEG 789 LEG 780	0136500000000000000000000000000000000000	17 26 251 0 1 0 0 66 0 0 0 3 132 149 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	23 162 407 0 18 450 155 21 2 0 38 194 197 887 893 68 41 197 897 893 68 41 391 62 294 4568 4395 438 4989 3226 4338 4989 3226 47 137 137 137 137 137 137 137 137 137 13	Traffic dis	stribution 0 1 2 1 1 2 0 2 1 10 0 0 0 0 0 0 0 0 0	77 12 237 228 21585 146 132 240 147 29 624 61 18 28 176 247 18 235 163 195 240 199 260 333 1255 1444 72 20 178 193 170 778 330 111 136 132 2431 117 116 22 18 18 18 18 18 18 19 19 19 10 10 11 11 11 11 11 11 11 11 11 11 11	148 111 36 120 760 177 123 4 1 9 112 3 0 0 3 7 7 6 5 5 12 4 9 112 3 0 0 3 7 7 6 5 5 12 4 9 112 12 12 12 12 12 12 12 12 12 12 12 12	265 213 948 46 68 708 68 709 289 171 79 246 148 79 206 430 111 115 111 121 97 69 70 529 157 10613 10469 9519 9466 88861 9035 10535 611 428 2279 314 13655 4015 1072 965 318 282 279 314 13655 4015 1072 965 314 1365 4017 328 147 151 94 278 309 414 290 482 278 309 414 290 482 830 420 2571 5285 322 117 110 999 130 39 446 1423 1433
Koute9_3 [0 FishingShip	OilProducts	CargoShip	PassengerShip	PleasureBoat	SupportShip	OtherShip	Sum

Table E.1: Northbound traffic

				Traffic di	stribution			
LEG 100 LEG 26 LEG 37 LEG 39 LEG 43 LEG 44 LEG 48 LEG 64 LEG 68 LEG 68 LEG 78 LEG 99 LEG 90 LEG 70 Route 11 7 Route 11 7 Route 12 Route 12 7 Route 12 7 Route 13 7 Route 17 Route 17 Route 17 Route 18 Route 19 Ro	0 0 3 11 3 0 10 0 0 10 0 0 0 0 0 0 0 0 0	27 119 0 0 0 0 105 0 0 105 0 0 174 157 0 0 0 2 1 0 0 0 7 174 157 0 0 0 1930 1940 1930 1942 1535 1639 2322 14 23 763 197 44 86 96 113 113 113 114 115 116 117 117 117 117 117 117 117 117 117	31 132 464 1 2 63 174 19 2 1 80 17 241 48 97 136 393 47 1390 43 390 43 390 43 390 43 390 43 43 43 44 19 24 19 24 19 24 19 24 19 24 10 24 10 24 10 24 10 24 10 24 10 24 10 26 10 27 10 10 10 10 10 10 10 10 10 10	0 112 10 0 3 4 4 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	021112221004000000000000000000000000000	103 200 2555 399 264 1500 233 360 181 13 566 106 58 41 41 39 109 153 538 495 2438 188 106 130 124 168 35 80 113 124 168 1504 122 49 21 226 2179 72 72 78 78 78 79 79 79 79 79 79 79 79 79 79 79 79 79	169 10 812 130 17 12 114 16 82 12 114 16 82 12 114 10 10 10 10 27 4483 310 2248 443 318 2248 248 248 248 225 531 12 11 10 10 10 10 10 10 10 10 10 10 10 10	330 176 11102 65 45 663 115 364 1184 106 194 549 470 59 134 120 186 38 301 17819 77719 77006 6823 583 60123 87 191 74 67 79 114 4153 1238 1030 1153 1238 1030 1153 1238 1153 1238 1153 1238 1153 1238 1153 1238 1153 1238 1238 1238 1238 1238 1238 1238 123
Route7-4 Route7-5 Route8-1 Route8-1 Route9-1 Route9-2 Route9-3	0 0 0 2 5 0 0 0 0 FishingShip	43 42 49 0 0 13 6 6	40 37 42 0 0 47 96 95 CargoShip	0 0 0 0 2 0 0 0 0	0 0 1 0 7 0 0 0 0	11 11 12 34 39 5 9 13 SupportShip	22 19 20 4 13 10 23 23 OtherShip	116 109 124 40 66 75 134 137
	1 isiningsinp	On rouncis	Cargosinp	1 assengersinp	1 icasuicibuat	SupportShip	Onicionip	Sulli

Table E.2: Southbound traffic

E.2 After scenario

				Traffic di	stribution			
LEG 100 LEG 26 LEG 29 LEG 37 LEG 43 LEG 44 LEG 48 LEG 64 LEG 87 LEG 87 LEG 88 LEG 89 LEG 94 Route 10 1 Route 11 1 Route 12 2 Route 12 2 Route 12 3 Route 12 3 Route 12 3 Route 12 4 Route 12 3 Route 12 1 Route 12 1 Route 12 3 Route 12 4 Route 13 1 Route 12 1 Route 13 1 Route 12 3 Route 14 1 Route 15 1 Route 16 1 Route 17 Route 17 Route 17 Route 18 Route 19 Route 20 Route 3 1 Route 4 1 Route 5 1 Route 6 1 Route 7 1 Route 7 2 Route 7 4 Route 7 5 Route 7 6 Route 7 1 Route 7 1 Route 7 2 Route 8 1 Route 9 1 Route 8 1 Route 9 1	0 1 3 6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	17 26 251 0 0 0 66 0 0 0 7 0 3 14 132 149 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	23 162 407 0 45 40 155 21 1 2 137 0 88 16 194 197 88 87 88 87 88 87 88 93 62 29 5163 5036 4561 39 4273 438 4561 376 247 177 186 207 513 376 217 127 127 137 147 147 147 157 157 157 157 157 157 157 157 157 15	0 0 12 1 0 0 3 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 1 2 1 2 0 2 1 10 0 3 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	77 12 237 28 585 19 46 132 23 240 197 147 262 561 18 28 31 255 21 248 133 76 533 471 248 235 169 248 120 26 30 333 125 1444 72 41 20 27 88 190 70 78 33 106 182 24 117 119 116 22 188 188 111 136 182 431 117 119 116 218 188 188 111 133 337	148 111 366 100 176 117 123 4 63 1 9 114 112 3 0 0 3 7 7 6 5 5 12 5 13 475 13 309 2489 2770 353 69 110 120 28 130 100 126 990 100 127 14 18 14 18 14 18 14 18 14 18 18 18 18 18 18 18 18 18 18 18 18 18	265 213 948 46 708 69 289 171 79 246 407 148 79 206 402 430 111 115 111 121 97 69 70 56 329 157 10681 10469 9474 8266 8861 10469 9474 8282 279 496 2106 430 471 1365 407 407 408 408 409 409 409 409 409 409 409 409 409 409
Route9 ¹ Route9 ² Route9 ³	0 0	14 17 13	104 92 124	0 0 1	2 0 0 0	33 37 7 11 9	17 23 26	142 143 173
	FishingShip	OilProducts	CargoShip	PassengerShip	PleasureBoat	SupportShip	OtherShip	Sum

Table E.3: Northbound traffic

				Traffic di	stribution			
LEG 100 LEG 26 LEG 29 LEG 37 LEG 43 LEG 44 LEG 47 LEG 58 LEG 68 LEG 68 LEG 794 Route 10 1 Route 11 2 Route 11 2 Route 12 1 Route 12 1 Route 13 2 Route 13 1 Route 1 1 Route 2 1 Route 3 1 Route 3 1 Route 3 1 Route 3 1 Route 4 1 Route 4 2 Route 5 1 Route 6 1 Route 7 1 Route 7 2 Route 7 1 Route 7 1 Route 7 1 Route 7 1 Route 7 2 Route 7 1 Route 7 1 Route 7 1 Route 7 2 Route 7 1 Route 7 2 Route 7 1 Route 7 2 Route 9 1 Route 9 2 Route 9 2 Route 9 3 Route 9 3	0 0 3 11 0 10 10 10 0 0 0 0 0 0 0 0 0 0	27 11 279 0 0 0 105 0 0 105 0 0 17 174 157 0 0 0 0 1931 1942 1931 19428 1535 12322 14 23 763 1948 288 966 1931 1428 1535 132 2 1 1 2 1 3 1 2 1 3 1 4 1 5 1 6 1 6 1 6 1 6 1 6 1 6 1 7 1 7 1 7 1 7 1 7 1 7 1 7 1 7 1 7 1 7	31 132 464 62 63 174 19 21 223 80 174 241 48 492 77 37 38 39 360 39 360 30 360 30 30 30 30 30 31 22 47 31 31 32 47 31 32 47 31 32 47 31 32 47 40 40 51 167 51 167 51 167 62 63 63 63 63 63 63 63 63 63 63	Traffic dis	stribution 0 2 1 1 2 2 1 0 4 0 5 0 1 0 2 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0	103 20 255 359 569 29 6150 223 360 227 181 13 56 106 54 8 41 419 153 57 564 495 243 188 106 130 124 168 1106 132 16 1504 122 421 250 179 72 78 31 109 1123 182 340 179 72 78 31 109 1124 1123 182 340 179 72 78 31 109 1124 1123 1124 1124 1125 1126 1127 1127 1127 1128 1129 1129 1129 1129 1129 1129 1129	169 10 818 110 819 1113 113 113 114 116 116 116 116 117 117 118 118 119 119 119 119 119 119 119 119	330 176 1102 65 663 115 361 171 364 555 134 106 194 57 58 63 58 151 7864 7719 6823 58447 5836 67123 132 236 67 7123 132 236 477 114 4153 1030 968 1158 477 11030 968 1158 477 11030
Koutes_5 [FishingShip	OilProducts	CargoShip	PassengerShip	PleasureBoat	SupportShip	OtherShip	Sum

Table E.4: Southbound traffic

F Results from frequency analysis

F.1 Ship-turbine collisions

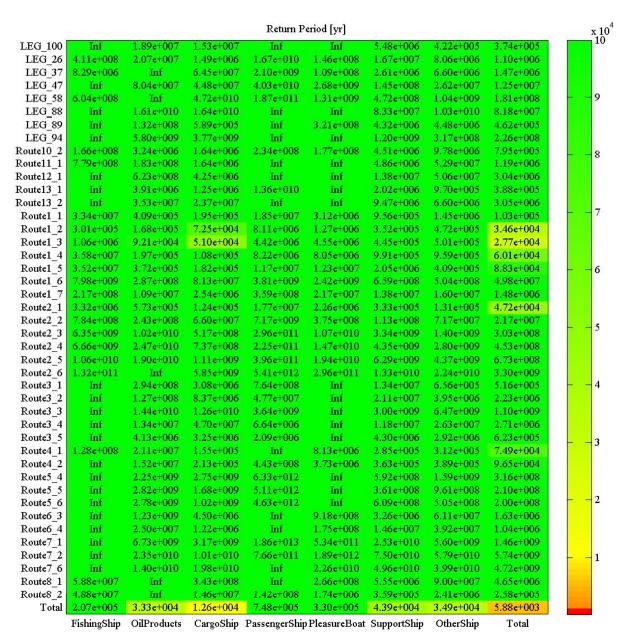


Figure F.1: Drifting turbine collisions

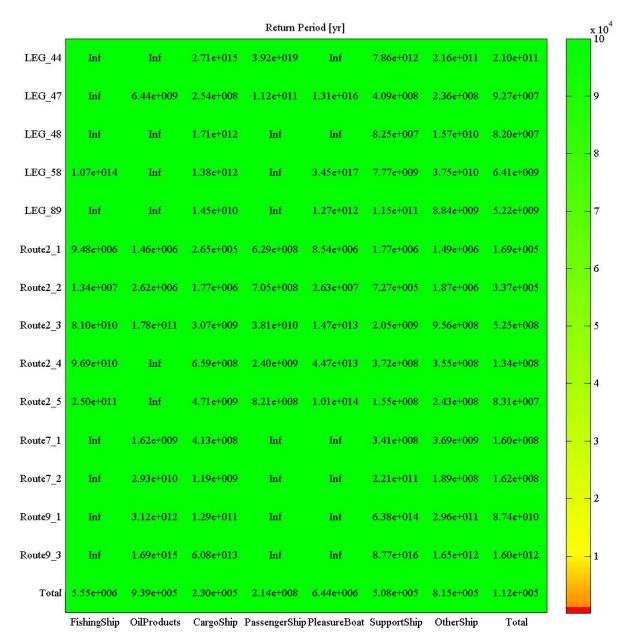


Figure F.2: Powered turbine collisions

F.2 Ship grounding incidents before

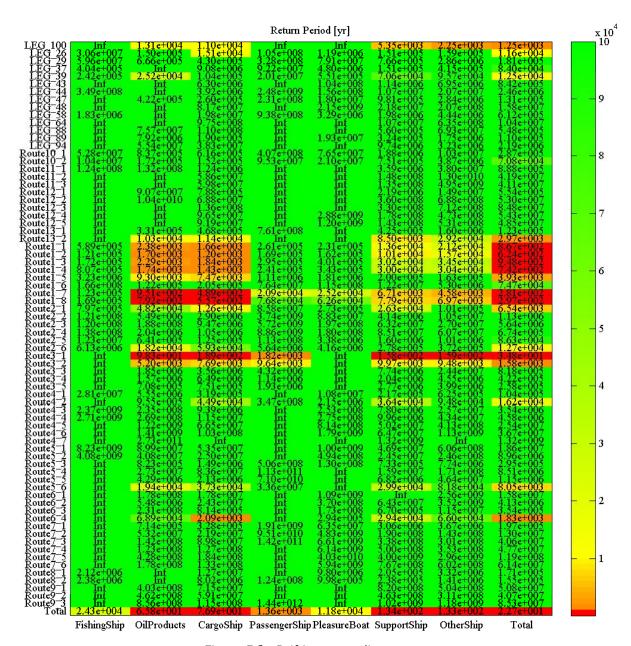


Figure F.3: Drifting groundings

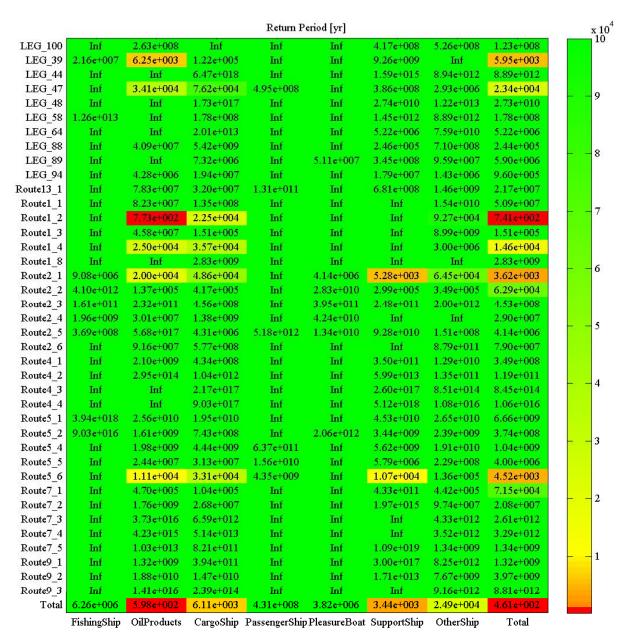


Figure F.4: Powered groundings

F.3 Ship grounding incidents After

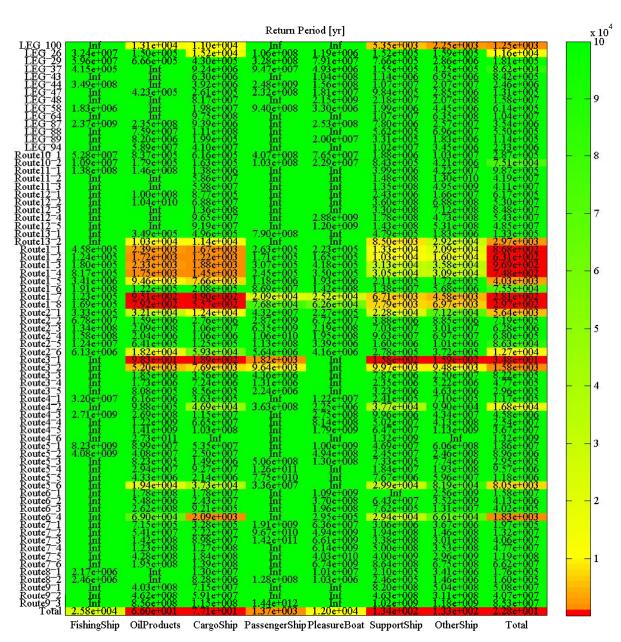


Figure F.5: Drifting groundings



Figure F.6: Powered grounding

F.4 Ship grounding incidents compared

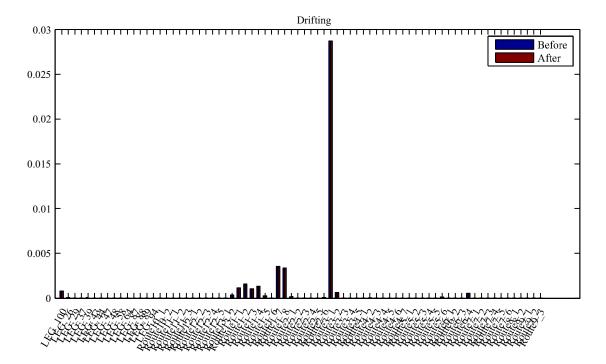


Figure F.7

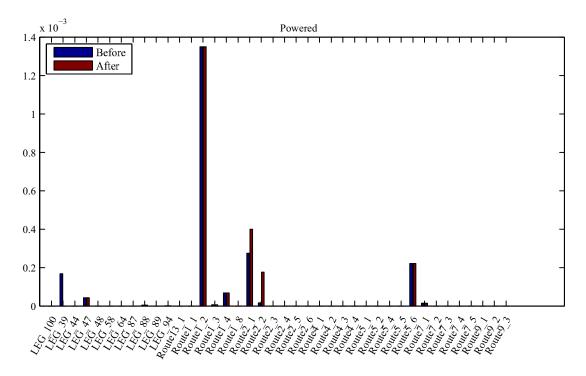


Figure F.8

F.5 Ship-ship collision incidents compared

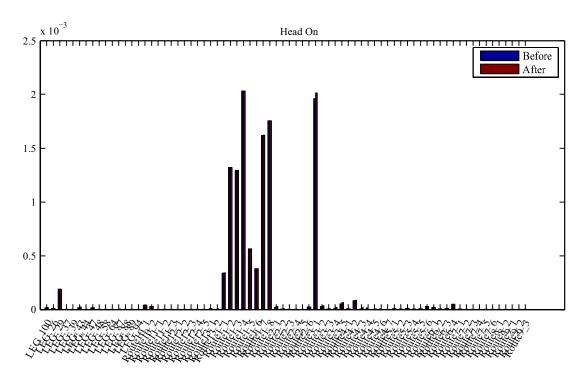


Figure F.9

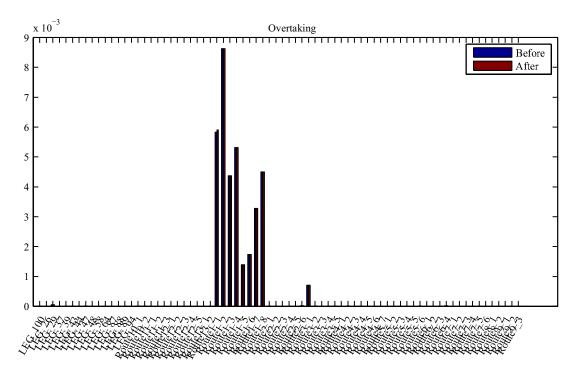


Figure F.10

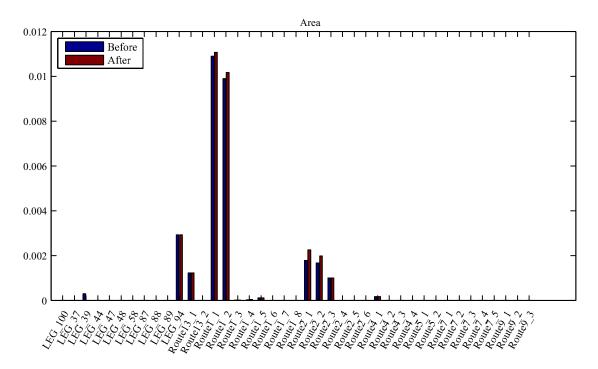


Figure F.11

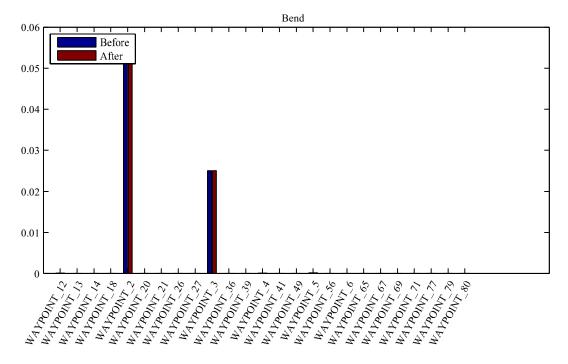


Figure F.12

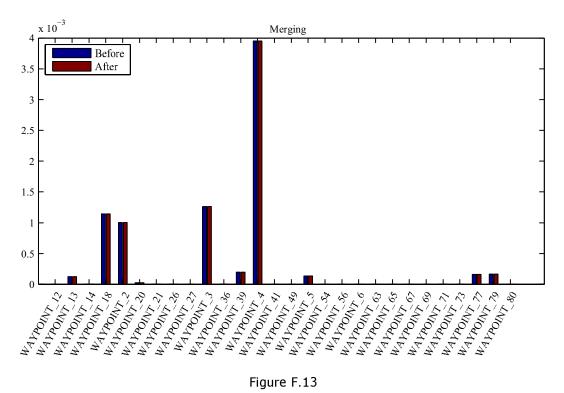


Figure F.13

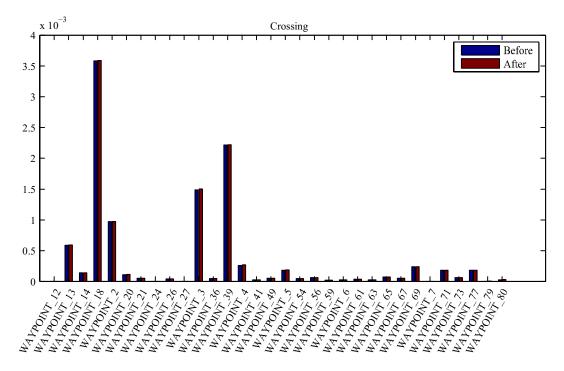


Figure F.14

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